

IVth International Conference on

Antenna Theory and Techniques

Volume 1

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IEEE AP/C/EMC/SP Kharkiv Joint Chapter of the Ukraine Section
Ministry of Education and Science of Ukraine

9 – 12 September 2003

Sevastopol, Ukraine

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**We wish to thank the following for their contribution to the success of
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Fiber Materials") of the Ukrainian Academy of Sciences

Technical Support

IEEE AP-S

Publishing House IPRZhR (Moscow, Russia)

Publishing House "Izvestiya Vuzov" (Kyiv, Ukraine)

Moscow Chapter IEEE

This material is based upon work supported by the European Office of Aerospace Research and
development under grant FA8655-03-15060

2003 International Conference on Antenna Theory and Techniques

IEEE Catalog Number:	03EX699
ISBN:	0-7803-7881-4
Library of Congress:	2003103227

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Table of Contents

06. THE OPTIMIZATION OF A SIGNAL PROCESSING IN RADAR WITH SCANNING ANTENNA ARRAY <i>A. D. Pluzhnikov, E. N. Pribludova</i>	352
07. SPACE-TIME PROCESSING IN THREE-DIMENSIONAL FORWARD SCATTERING RADAR <i>A. V. Myakinkov, A. G. Ryndyk</i>	355
08. THE ROBUST SPATIOTEMPORAL FILTERING OF SIGNALS IN CORRELATED NOISE <i>O. V. Sytnik</i>	359
09. HYBRID OPTOELECTRONIC PROCESSOR FOR DETECTION, DIRECTION FINDING AND RECEPTION OF COMPLEX SIGNALS <i>A. Yu. Grinev, D. V. Bagno, V. V. Rozdobudko, V. S. Temchenko</i>	362
10. ANTENNA ARRAY SIGNAL PROCESSING WITH SUPERRESOLUTION BY 2-D UNITARY TLS -ESPRIT WITH STRUCTURE WEIGHTING <i>V. I. Vasylyshyn</i>	366
11. QUALITATIVE INDICES OF THE METHOD OF DETERMINING THE NUMBER OF SIMULTANEOUSLY ACTING SIGNALS <i>N. M. Nikitin, L. G. Shatsman</i>	370
12. CORRECTION OF SMART ANTENNAS RECEIVING CHANNELS CHARACTERISTICS FOR 4G MOBILE COMMUNICATIONS <i>V. I. Slyusar, I. V. Titov</i>	374
13. THE VARIANT OF EQUATION OF DIRECTION FINDING CHARACTERISTIC OF THE AMPLITUDE SUM-DIFFERENCE DIRECTION FINDER <i>V. A. Kryachko</i>	376
14. THE PERSPECTIVE DIRECTIONS OF THE TECHNICAL MODERNIZATION OF INTER-PERIOD SIGNAL PROCESSING SYSTEMS OF PULSE ATC RADARS <i>D. I. Lekhovitsky, V. I. Zaritsky, I. G. Kirillov, S. I. Burkovsky</i>	378
15. MEASUREMENTS OF RECEPTION DIRECTION OF DETERMINISTIC SIGNAL AGAINST SPATIALLY-CORRELATED INTERFERENCES WITH THE USE OF THE ADAPTIVE ANTENNA ARRAY <i>S. T. Bagdasaryan, V. A. Tarshin, V. A. Vasilyev</i>	381
16. ALGORITHM OF SPATIAL SELECTION OF UNCORRELATED SIGNALS <i>O. Z. Sultanov</i> ...	384
17. THE METHOD OF DETERMINATION OF THE AMPLITUDE AND PHASE DISTRIBUTION IN ANTENNA APERTURE PLANE <i>I. B. Shirokov</i>	387
18. COMPUTER SIMULATION OF TARGET BACKSCATTERING AS ELEMENT OF PERSPECTIVE RADAR DESIGN <i>S. P. Leshchenko, V. M. Orlenko, Y. D. Shirman</i>	389
19. COMBINED DIRECTION FINDERS OF NOISE RADIATION SOURCES BASED ON ADAPTIVE LATTICE FILTERS <i>D. I. Lekhovitsky, D. V. Atamansky, V. V. Djus, N. A. Staheev</i>	394
20. PERFECTION OF THE ALGORITHM FOR UNCORRELATED SIGNALS ANGULAR DISCRIMINATION BY MEANS OF WAVELET TRANSFORMATION <i>L. A. Titarenko, B. Yu. Bordjugov</i>	398
21. EFFECTIVE PARAMETER ESTIMATION OF EXPONENTIAL SIGNALS IN ADAPTIVE ARRAYS <i>M. V. Andreev, O. O. Drobakhin</i>	401
22. MULTI-BASE INSAR WITH ENHANCED SIGNAL PROCESSING <i>A. V. Ksendzuk, V. K. Volosyuk</i>	405
23. PHASED ANTENNA ARRAY WITH EXCITATION ADAPTIVE TO CONSTRUCTION DISTORTIONS <i>U. R. Liepin, D. V. Karlov, G. A. Golovin, N. N. Petrushenko</i>	409
24. AN ADAPTIVE PARAMETER ESTIMATION OF GAUSSIAN SIGNAL IN THE PRESENCE OF AN UNKNOWN GAUSSIAN NOISE <i>V. I. Turchin</i>	411

CORRECTION OF SMART ANTENNAS RECEIVING CHANNELS CHARACTERISTICS FOR 4G MOBILE COMMUNICATIONS

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Abstract

The paper considers a way of correction of the reception channels characteristics for smart-antennas in 4G mobile communications.

Keywords: smart-antenna, mobile communications, digital beam formings, correction coefficients, digital antenna array, calibrating source, base station.

The key technology of 4G mobile communications systems is adaptive digital beam forming for smart antennas. Adaptive array technology provide for high gain systems, in turn optimizing handset size and power consumption, and at the same time reduce possible interference effects from other terminals in the same cell area. Software radio technology of smart antennas also enable multimode and multi band operation for base stations [1].

For errors minimization of digital beam formings communications systems with nonidentical channels of antenna arrays arises a problem of correction of the reception channels characteristics.

For the solution of the given problem it is proposed to operate by a special external submission of the pilot-signal. To minimize the hardware expenditures it is proposed to use as a the pilot-signal a signals from other base stations in the same cell area (Fig. 1).

When applied a pilot-signal from only one base station, as a correction procedures for square smart an-

tennas is proposed to use a method [2]. In the general case the correction process is consisted in weighing the digital voltages in receiving channels by complex weight coefficients:

$$\begin{aligned} \dot{U} \cdot \dot{\alpha}_{cor} &= (U^c + j \cdot U^s)(\alpha_{cor}^c + j \cdot \alpha_{cor}^s) =, (1) \\ &= (U^c \alpha_{cor}^c - U^s \alpha_{cor}^s) + j(\alpha_{cor}^s U^c + U^s \alpha_{cor}^c) \end{aligned}$$

where $\alpha_{cor}^c, \alpha_{cor}^s$ – quadratic components of correction coefficient, U^c, U^s – quadratic components of response of the primary digital antenna arrays (DAA) channels.

In the case of square smart antennas with $R \times Q$ elements the quadratic components of correction coefficient must be calculated for a set of N readings of pilot-signal from base station with number "m":

$$\begin{aligned} \alpha_{rqm}^c &= \frac{\sum_{n=1}^N \{U_{rqn}^c \beta_{rqm,n}^c + U_{rqn}^s \beta_{rqm,n}^s\}}{\sum_{n=1}^N (U_{rqn}^c{}^2 + U_{rqn}^s{}^2)}, (2) \\ \alpha_{rqm}^s &= \frac{\sum_{n=1}^N \{U_{rqn}^c \beta_{rqm,n}^s - U_{rqn}^s \beta_{rqm,n}^c\}}{\sum_{n=1}^N (U_{rqn}^c{}^2 + U_{rqn}^s{}^2)}, \end{aligned}$$

where $\beta_{rqm,n}^s, \beta_{rqm,n}^c$ – quadratic components of a measurement standards response of the rq -th primary smart antennas channels in the n -th time interval, $\alpha_{rqm}^s, \alpha_{rqm}^c$ – quadratic components of correction coefficient for rq -th primary smart antennas channels, which calculate for a pilot-signal from base station with number "m", U_{rqn}^s, U_{rqn}^c – quadratic compo-

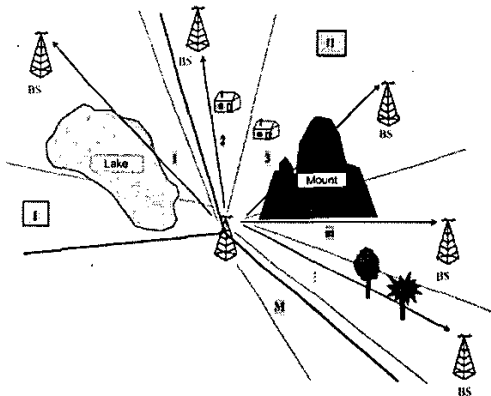


Fig. 1.

nents of response of the rq -th primary smart antennas channels in the n -th time interval,

$$\beta_{rqm,n}^c = a_n^c \cos(X) - a_n^s \sin(X),$$

$$\beta_{rqm,n}^s = a_n^s \cos(X) + a_n^c \sin(X), \quad X = x_{rm} + x_{qm},$$

x_{rm}, x_{qm} – generalized coordinates of calibrating source (base station with number "m") with respect to DAA normal,

$$x_{rm} = \frac{2\pi}{\lambda} d_r \left(r - \frac{R+1}{2} \right) \sin \theta_m \cdot \cos \varepsilon_m,$$

$$x_{qm} = \frac{2\pi}{\lambda} d_q \left(q - \frac{Q+1}{2} \right) \sin \theta_m \cdot \sin \varepsilon_m,$$

λ – wavelength of calibrating source carrier, d_r, d_q – the distance between array's elements in a row and in a column correspondingly, R, Q – number of array's elements in a row and in a column, θ, ε – angle coordinates of the calibrating source with respect to DAA normal, $a_n^c = U_{sT_n}^c, a_n^s = U_{sT_n}^s$ – quadratic components of response of the standard primary smart antennas channel in the n -th time interval.

In the case of linear digital antenna array use a correction coefficients only for one angle plane:

$$\alpha_{rm}^c = \frac{\sum_{n=1}^N \{ U_{rn}^c \beta_{rm,n}^c + U_{rn}^s \beta_{rm,n}^s \}}{\sum_{n=1}^N (U_{rn}^c + U_{rn}^s)},$$

$$\alpha_{rm}^s = \frac{\sum_{n=1}^N \{ U_{rn}^c \beta_{rm,n}^s - U_{rn}^s \beta_{rm,n}^c \}}{\sum_{n=1}^N (U_{rn}^c + U_{rn}^s)},$$
(3)

where $\beta_{rm,n}^s, \beta_{rm,n}^c$ – quadratic components of a measurement standards response of the r -th primary smart antennas channels in the n -th time interval, $\alpha_{rm}^s, \alpha_{rm}^c$ – quadratic components of correction coefficient for r -th primary smart antennas channels, which calculate for a pilot-signal from base station with number "m", U_{rn}^s, U_{rn}^c – quadratic components of response of the r -th primary smart antennas channels in the n -th time interval,

$$\beta_{rm,n}^c = a_n^c \cos(x_{rm}) - a_n^s \sin(x_{rm}),$$

$$\beta_{rm,n}^s = a_n^s \cos(x_{rm}) + a_n^c \sin(x_{rm}),$$

x_{rm} – generalized coordinate of calibrating source (base station with number "m") with respect to DAA normal,

$$x_{rm} = \frac{2\pi}{\lambda} d \left(r - \frac{R+1}{2} \right) \sin \theta_m,$$

λ – wavelength of calibrating source carrier, d – the distance between array's elements in a row and in a column correspondingly, R – number of array's elements, θ – angle coordinate of the calibrating source with respect to DAA normal.

When applied a pilot-signal from more base stations, for a correction procedures can be used a average correction coefficient:

$$\alpha_{cor}^{c(s)} = \frac{1}{M} \sum_{m=1}^M \alpha_{rqm}^{c(s)}. \quad (4)$$

The most effective way of correction is use of a more pilot-signals from M base stations in the one time interval. In this case must be used a correction coefficients:

$$\alpha_{rq}^s = \frac{\sum_{n=1}^N \left\{ U_{rq_n}^c \sum_{m=1}^M \beta_{rqm}^s - U_{rq_n}^s \sum_{m=1}^M \beta_{rqm}^c \right\}}{\sum_{n=1}^N (U_{rq_n}^c + U_{rq_n}^s)},$$

$$\alpha_{rq}^c = \frac{\sum_{n=1}^N \left\{ U_{rq_n}^c \sum_{m=1}^M \beta_{rqm}^c + U_{rq_n}^s \sum_{m=1}^M \beta_{rqm}^s \right\}}{\sum_{n=1}^N (U_{rq_n}^c + U_{rq_n}^s)},$$
(5)

where

$$\beta_{rqm}^c = a_m^c \cos(x_{rm} + x_{qm}) - a_m^s \sin(x_{rm} + x_{qm}),$$

$$\beta_{rqm}^s = a_m^s \cos(x_{rm} + x_{qm}) + a_m^c \sin(x_{rm} + x_{qm}),$$

$$a_m^c = \text{Re}[A_m], \quad a_m^s = \text{Im}[A_m],$$

$$[A_m] = [P^* P]^{-1} P^* \hat{U},$$

$$P = \begin{bmatrix} f_1(\omega_1) & f_1(\omega_2) & \dots & f_1(\omega_M) \\ f_2(\omega_1) & f_2(\omega_2) & \dots & f_2(\omega_M) \\ \vdots & \vdots & \vdots & \vdots \\ f_N(\omega_1) & f_N(\omega_2) & \dots & f_N(\omega_M) \end{bmatrix} - \text{matrix of}$$

amplitude-frequency characteristics meanings of N FFT-filters for a measurement standards reception channels;

$$f_n(\omega_m) = \frac{\sin N(\omega_m - \omega_n)}{\sin(\omega_m - \omega_n)},$$

ω_n – the central frequency of n -th FFT-filter, U – vector of voltages of the responses channels.

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Authors List

Rodenko S. N. 42
Rodionov A. A. 414
Roenko A. N. 572
Rogulyev V. A. 47
Roshchin V. V. 171, 173
Rospopa V. O. 229
Rozdobudko V. V. 362
Ruban V. P. 553
Ruchenkov V.A. 171, 173
Rucker H. 631
Rudakov V. I. 813, 828
Rudenko V. N. 323
Rudnik A. G. 261
Rybalko A. M. 846
Ryndyk A. G. 355

S

Salamatin V. V. 577
Saprykin S. D., 47
Savenko P. A. 708
Savochkin A. A. 751
Sazonov A. Z. 657
Sedyshev P. Yu. 42
Sedyshev Yu. N. 42
Semchuk A. Yu. 674
Semenikhina D. V. 837
Semenova E. K. 178
Sestoretzkii B.V. 171, 173
Shakhbazov V. G. 821, 823
Shamanov A. N. 535
Shaposhnikov S. S. 809
Sharygin G.S. 587
Sharygina L. I. 587
Shatrov A. D. 809
Shatsman L. G. 370
Shckorbatov Yu. G. 821, 823
Shevchenko D. V. 651
Shigesawa H. 52
Shilo S. A. 671, 701
Shifrin Ya. S. 81
Shirman Y. D. 389
Shirokov I. B. 387
Shishkova A. V. 465
Shishlov A. V. 87, 264
Shitikov A. M. 87, 761
Shkvarko Yu. V. 97, 527, 531
Shokalo V. M. 846
Shrenk O. E. 255

Shubny A. I. 251
Shubov A. G. 87
Shugurov A. S. 818
Shulga S. N. 785, 830
Shurda G. G. 807
Sibruk L. V. 742
Sidorenko Y. B. 300
Sin'kov V. V. 692
Sinyavsky G. P. 769
Sirenko K. Yu. 110
Sirenko Yu. K. 110, 705
Sitsko N. U. 723
Skobelev S. P. 477
Skresanov V. N. 251, 290
Slyozkin V. G. 501, 504
Slyusar V. I. 374
Soleimani M. 509
Solonskaya S. V. 834
Solyanik O. 856
Soroka A. S. 261
Soshenko V. A. 692
Sosulnikov V. P., 47
Staheev N. A. 394
Starostenkov E. A. 47
Stepanenko P. Y. 590, 796, 799
Storozh V. G. 512
Strelchenko V. I. 834
Sugonyak Z. V. 742
Sukharevsky O. I. 657
Sukhomlinov D. V. 842
Sultanov O. Z. 384
Suserov Yu. A. 87
Syrotyuk V. H. 233
Sytnik O. V. 359
Syvozalizov M. A. 726
Szafran M. 687

T

Takano T. 63
Tapia-Sanchez D. 337
Tarshin V. A. 381
Temchenko V. S. 362
Tereschenko V. M. 590, 796, 799
Tereshchenko A. I. 805
Titarenko L. A. 398
Titov A. A. 556
Titov A. N. 556

Authors List

<i>Titov I. V.</i>	374	<i>Voronin E. N.</i>	296
<i>Tkachenko A. A.</i>	664	<i>Voskresensky D. I.</i>	77, 617
<i>Tkachenko V.</i>	779	<i>Vuntsemeri V. S.</i>	782
<i>Tkalich N. V.</i>	677, 701	<i>Vyazmitinov I. A.</i>	300
<i>Tkalich V. G.</i>	818	<i>Vyazmitinova A. I.</i>	110
<i>Tofani G.</i>	628		
<i>Tokarsky P. L.</i>	161	Y	
<i>Topchev M. D.</i>	677	<i>Yakovenko Eu.</i>	825
<i>Tretyakov O. A.</i>	605	<i>Yanenko A. F.</i>	816
<i>Tripp V.</i>	25	<i>Yanovsky F. J.</i>	71
<i>Troitskiy A. V.</i>	491	<i>Yarovoy A. G.</i>	21
<i>Trubin A.</i>	801	<i>Yarovoy S. V.</i>	417
<i>Tsuji M.</i>	52	<i>Yashchyshyn Ye.</i>	687
<i>Turchin V. I.</i>	411, 414	<i>Yatsenko E. O.</i>	156
<i>Tuz V. R.</i>	775	<i>Yatsenko N. M.</i>	156
<i>Tymchuk V. Y.</i>	644	<i>Yatskevcich V.</i>	310
<i>Tyschuk U. N.</i>	474	<i>Yatsuk L. P.</i>	125
		<i>Yatsunenka A. G.</i>	818
U		<i>Yefimova Y. V.</i>	327
<i>Ulyanov Yu. N.</i>	564	<i>Yeliseyeva N. P.</i>	459
<i>Umzar Y. A.</i>	261	<i>Yena G. A.</i>	590
<i>Usichenko A. V.</i>	789, 261	<i>Yermakov G. V.</i>	558
<i>Usin V. A.</i>	745, 748	<i>Yevdokymov A. P.</i>	307
<i>Usina A. V.</i>	748	<i>Yukhanov Yu. V.</i>	117, 121
		<i>Yurchenko L. V.</i>	792
V		<i>Yurchenko V. B.</i>	237, 792
<i>Vaganov R. B.</i>	809		
<i>Vaate Bij</i>	633	Z	
<i>Valsecchi G.</i>	611, 624	<i>Zabolotniy P. I.</i>	818
<i>Varyanitzza-</i>		<i>Zagorin G. K.</i>	130
<i>Roshchupkina L. A.</i>	152	<i>Zaichenko O. B.</i>	754
<i>Vaschenko V. F.</i>	677	<i>Zakharia Y. A.</i>	512
<i>Vasilchenko I. I.</i>	701	<i>Zamiatin V. I.</i>	327
<i>Vasilyev V. A.</i>	381	<i>Zamorska O. F.</i>	199
<i>Vasylyshyn V. I.</i>	366	<i>Zamyatin V. I.</i>	558
<i>Vazquez-Bautista R. F.</i>	531	<i>Zapunidi S. A.</i>	561
<i>Veelen M.</i>	633	<i>Zaritsky V. I.</i>	378
<i>Velasco G.</i>	539	<i>Zarudnev I. I.</i>	644
<i>Velasco V. M.</i>	539	<i>Zatserklyany A. E.</i>	570
<i>Vesnik M. V.</i>	149	<i>Zheng Yu.</i>	605
<i>Vinogradov J. V.</i>	796	<i>Zhirnov V. V.</i>	834
<i>Vinogradov V. A.</i>	561	<i>Zhironkin Yu. V.</i>	125
<i>Vladimirov D.</i>	682	<i>Znamenshchikov O. V.</i>	830
<i>Vladimirov N. V.</i>	87	<i>Zvezdina M. Yu.</i>	134, 138, 141
<i>Volkov V. M.</i>	754	<i>Zvyagintsev A.A.</i>	719
<i>Volosuyk V. K.</i>	405, 539		
<i>Vorobjov R. V.</i>	268		